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**Contingent solutions to the center manifold equation.** (English) Zbl 0745.34039  
*Ann. Inst. Henri Poincaré, Anal. Non Linéaire* 9, No. 1, 13-28 (1992).

For a system of ordinary differential equations

$$x'(t) = f(x(t), y(t)), \quad y'(t) = -\lambda y(t) + g(x(t), y(t)),$$

where  $X, Y$  are finite dimensional vector spaces,  $f : X \times Y \rightarrow X$  and  $g : X \times Y \rightarrow Y$  are Lipschitzian maps and  $\lambda > 0$ , the authors characterize a center manifold  $r : X \rightarrow Y$  as a solution of the quasi-linear first order system of “contingent” partial differential inclusions (1)  $\lambda r(x) \in g(x, r(x)) - Dr(x)(f(x, r(x)))$  (where  $D$  denotes the contingent derivative). They show that there exists a global bounded and Lipschitzian contingent solution to (1) if  $\|g(x, y)\| \leq c(1 + \|y\|)$  is satisfied and  $\lambda$  is large enough. Furthermore they prove that this solution can be approximated in the spirit of the “viscosity method” by a solution  $r_\varepsilon$  to the second-order system  $\lambda r(x) = \varepsilon \Delta r(x) - r'(x)f(x, r(x)) + g(x, r(x))$  when  $\varepsilon \rightarrow 0$ .

Reviewer: [W.Müller \(Berlin\)](#)

**MSC:**

- [34C30](#) Manifolds of solutions of ODE (MSC2000)
- [35R70](#) PDEs with multivalued right-hand sides
- [35A35](#) Theoretical approximation in context of PDEs

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**Keywords:**

[ordinary differential equations](#); [center manifold](#); [partial differential inclusions](#); [contingent derivative](#); [global bounded and Lipschitzian contingent solution](#); [viscosity method](#)

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