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Roughness of linear dynamical systems. II. (English. Russian original) Zbl 0805.93023

Autom. Remote Control 53, No. 1, Pt. 1, 34-43 (1992); translation from *Avtom. Telemekh.* 1992, No. 1, 41-52 (1992).

Summary: [For the first part see *ibid.* 52, No. 11, pt. 1, 1493-1498 (1991); translation from *Avtom. Telemekh.* 1991, No. 11, 17-23 (1991; Zbl 0793.93056).]

A test for the roughness of linear stationary systems is formulated as well as some of its consequences. Examples of the study of roughness are considered.

MSC:

93C05 Linear systems in control theory

Cited in 1 Document

Keywords:

roughness; linear stationary systems