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***N*-dimensional shape optimization under capacity constraint.** (English) Zbl 0847.49029
J. Differ. Equations 123, No. 2, 504-522 (1995).

The shape optimization problem

Minimize

$$J(\Omega) = \frac{1}{2} \int_B (u_\Omega - g)^2 dx, \tag{1}$$

subject to

$$-\mathcal{A}u_\Omega = f \tag{2}$$

is considered. The following notations are chosen:

Let $B \subset \mathbb{R}^N$ be an open ball, $A \in M_{n \times n}(C^1(\overline{B}))$, $A = A^*$, $\alpha I \leq A \leq \beta I$, $0 < \alpha < \beta$. Further, the associated operator $\mathcal{A} : H_0^1(B) \rightarrow H^{-1}(B)$ with $\mathcal{A} = \operatorname{div}(A\nabla)$ is defined. $f \in H^{-1}(B)$ and the open subset Ω of B are considered. The state equation (2) has to be understood in the variational sense.

The existence of extremal domains of problem (1)–(2) is investigated. Especially, relations between finding of *compact sets* in some topology on the space of domains and the *continuity* of the map $\Omega \mapsto J(\Omega)$ is discussed.

The authors obtain results for the *N*-dimensional case for classes of domains satisfying *capacity density conditions*.

Reviewer: [H.Goldberg \(Chemnitz\)](#)

MSC:

[49Q10](#) Optimization of shapes other than minimal surfaces

[49J20](#) Existence theories for optimal control problems involving partial differential equations

Cited in **26** Documents

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