

**Nikitin, S.**

**Decoupling normalizing transformations and local stabilization of nonlinear systems.** (English) [Zbl 0863.34013](#)

Math. Bohem. 121, No. 2, 225-248 (1996).

Systems of the form

$$\frac{d}{dt}x = Ax + \Phi(x, y),$$

$$\frac{d}{dt}y = By + \Psi(x, y)$$

are investigated where  $x \in \mathbb{R}^m, y \in \mathbb{R}^n, A \in L(\mathbb{R}^m, \mathbb{R}^m)$  is a linear operator on  $\mathbb{R}^m$  with  $A = -A^T$ , the eigenvalues of  $B \in L(\mathbb{R}^n, \mathbb{R}^n)$  have negative parts,  $\Phi, \Psi$  are at least  $C^3$  vanishing together with their derivatives at the origin. It is shown that there is a normalizing transform completely decoupling the stable and center manifold dynamics of the system into two independent systems of the form

$$\frac{d}{dt}\tilde{x} = A\tilde{x} + \tilde{\Phi}(\tilde{x}, h(\tilde{x})),$$

$$\frac{d}{dt}\tilde{y} = B\tilde{y} + \tilde{\Psi}(\tilde{x}, \tilde{y}).$$

Some conditions for the local stabilization of the system are presented.

Reviewer: Š.Schwabik (Praha)

**MSC:**

- [34A34](#) Nonlinear ordinary differential equations and systems, general theory
- [34D05](#) Asymptotic properties of solutions to ordinary differential equations
- [34D35](#) Stability of manifolds of solutions to ordinary differential equations
- [93C10](#) Nonlinear systems in control theory

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nonlinear system; stabilization; center manifold; normalizing transformation; smooth feedback

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