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A proof of the Dirac conjecture for a class of finite-dimensional Hamilton-Dirac systems.
(English. Russian original) [Zbl 1040.70011](#)

Math. Notes 71, No. 5, 724-729 (2002); translation from *Mat. Zametki* 71, No. 5, 793-797 (2002).

This paper is devoted to constrained Hamiltonian systems. By definition constraints in a neighborhood of a point $x_0 \in \mathbb{E}$ is a map $\phi : \mathbb{E} \rightarrow \mathbb{E}_\phi$ satisfying the following conditions:

- a) ϕ is continuously differentiable in a neighborhood of the point x_0 and $\phi(x_0) = 0$;
- b) the map $\phi'(x_0) : \mathbb{E} \rightarrow \mathbb{E}_\phi$ is surjective.

Here $\mathbb{E}, \mathbb{E}_\phi$ are the Euclidean spaces. A Dirac Hamiltonian system on the phase space \mathbb{E} is a set (H, ϕ, \mathbb{E}, I) , where $H \in C^\infty(\mathbb{E}, \mathbb{R}^1)$, $\phi : \mathbb{E} \rightarrow \mathbb{E}_\phi$ is a constraint, \mathbb{E} is an even-dimensional Euclidean space, and $I : \mathbb{E} \rightarrow \mathbb{E}$ is a symplectic operator. The author introduces the Dirac class, and within this class proves the classical Dirac conjecture. The proof is based on the theory of control systems.

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MSC:

[70H45](#) Constrained dynamics, Dirac's theory of constraints

[70Q05](#) Control of mechanical systems

Keywords:

[Dirac class](#); [phase space](#); [symplectic operator](#); [control system](#); [constrained Hamiltonian system](#)

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