

Casas, Eduardo

Control of an elliptic problem with pointwise state constraints. (English) Zbl 0606.49017
SIAM J. Control Optimization 24, 1309-1318 (1986).

The paper deals with a control problem for an elliptic equation of second order $Ay = v$ on Ω , $y = 0$ on $\partial\Omega$. The cost functional is of the form

$$J(v) = \int_{\Omega} (y(v) - y_0)^2 dx + (r/2) \int_{\Omega} v^2(x) dx, \quad v \in K$$

where K is a convex closed subset of $L^2(\Omega)$, $y_0 \in L^2(\Omega)$. The following control problem is solved: minimize $J(v)$ for $v \in K$ and $|y(v, x)| \leq 1$ for all $x \in \Omega$.

The existence and uniqueness of a solution is proved. Optimality conditions are given and regularity of the optimal solution is investigated.

Reviewer: [I.Bock](#)

MSC:

- [49K20](#) Optimality conditions for problems involving partial differential equations Cited in **103** Documents
- [35J25](#) Boundary value problems for second-order elliptic equations
- [49J20](#) Existence theories for optimal control problems involving partial differential equations
- [35B37](#) PDE in connection with control problems (MSC2000)
- [35D10](#) Regularity of generalized solutions of PDE (MSC2000)
- [46E35](#) Sobolev spaces and other spaces of "smooth" functions, embedding theorems, trace theorems
- [93C20](#) Control/observation systems governed by partial differential equations

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pointwise state constraints; elliptic equation of second order; existence and uniqueness; Optimality conditions; regularity

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