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Some cases of chaotic representation. (Quelques cas de représentation chaotique.) (French)

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[For the entire collection see Zbl 0733.00018.]

The author considers a martingale X with respect to a filtration (\mathcal{F}_t) such that $\langle X, X \rangle_t = t$; (\mathcal{N}_t^X) is the corresponding natural filtration of X . Let S be the disjoint union of all S_n , $n \geq 0$, where $S_n \subset (0, \infty)^n$ is the set of all n -element subsets of $(0, \infty)$, with their elements written in an ascending order, and let λ be the direct sum of the corresponding Lebesgue measures. There is a linear isometric mapping $f \rightarrow \int f dX$ from $L^2(S, \lambda)$ to L^2 ; let $H(X)$ be its image. A more general stochastic integral $\int \chi_{\mathcal{A}_T} f dX$ is defined, for every $f \in L^2(\mathcal{B}(S) \otimes \mathcal{F}_T)$ null outside $\mathcal{A}_T = \{(A, \omega); A \subset (T(\omega), \infty)\}$, where T is a stopping time; in its definition (X_{T+t}) is used. Let $H^T(X)$ be its image. If \mathcal{N}_0^X is trivial and for every (\mathcal{N}_t^X) -martingale M_t there is an \mathcal{N}^X -previsible ϕ with $dM_t = \phi_t dX_t$, then X is said to have PRP (propriété de représentation prévisible), while, if $H(X)$ is the whole $L^2(\mathcal{N}_\infty^X)$, X is said to have PRC (... chaotique).

The main purpose of this paper is to give new examples of X 's having PRC (there are 7 quotations with such examples). The first is $Z_t = X_t$ for $t \leq T$, $Z_t = X_T + Y_{t-T} - Y_0$ for $t \geq T$, where X, Y are independent, both having PRC, and T is an (\mathcal{N}_t^X) -stopping time. The second is a Y for which there exist X^n having PRC and $(\mathcal{N}_t^{X^n})$ -stopping times T_n such that $Y = X^n$ on $[0, T_n]$ and $\sup T_n = \infty$. The third is an X having PRP, with $\langle X, X \rangle_t = t$, $d[X, X]_t = dt + \phi_t dX_t$, ϕ being previsible, nowhere null, with $\int \chi_{[0,t]}(s) \phi_s^{-2} ds < \infty$ for all t . The fourth is X from the solution (X, E) (its existence and unicity in law are shown) of $d[X, X]_t = dt + dE_t$, $dE_t = E_{t-} \lambda dX_t$, $X_0 = x$, $E_0 = e$, where λ, x, e are constants. The proofs begin by "Proposition 1", relative to two martingales X, Y with $\langle X, X \rangle_t = \langle Y, Y \rangle_t = t$ and $X = Y$ on $[0, T]$, T being a stopping time. In the last statement of this proposition, X is PRC and T is an (\mathcal{N}_t^X) -stopping time. Proposition 1 involves also $g = C_T(U, X)$, $h = C(U, X)$ for $U \in L^2$, where the projections of U on $H^T(X)$ and $H(X)$ are $\int \chi_{\mathcal{A}_T} g dX$, $\int h dX$, respectively. The paper finishes with other two results. The first expresses $C(U, X)$ using $C(V, X)$'s with \mathcal{F}_T -measurable V 's and $C_T(U, X)$ and the second proves that a sufficient condition for $U \in H(X)$ is that X has PRP and $\int E(C_{\inf A-}(A)^2) \lambda(dA) < \infty$, where $dC_t(A) = \Gamma_t(A) dX_t$ and, for $A = \{\dots < b < c\}$, $C_t(A)$ is $E(U; \mathcal{F}_t)$ for $t \geq c$, and $E(\Gamma_c(A); \mathcal{F}_t)$ for $t \in [b, c)$ etc.

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MSC:

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60H05 Stochastic integrals

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