

Sattayatham, P.

Strongly nonlinear impulsive evolution equations and optimal control. (English)

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Nonlinear Anal., Theory Methods Appl., Ser. A, Theory Methods 57, No. 7-8, 1005-1020 (2004).

The system is described by the evolution equation

$$x'(t) + A(t, x(t)) = g(t, x(t)) + B(t)u(t)$$

satisfied in an interval $0 < t < T$ minus a finite set $\{t_k\}$, $0 < t_1 < t_2 < \dots < t_n < T$. The solution satisfies an initial condition at $t = 0$ and jump conditions at the other points,

$$x(0) = x_0, \quad x(t_k^+) - x(t_k) = F_k(x(t_k)), \quad k = 1, 2, \dots, n.$$

The author discusses existence of solutions to a control problem that consists of minimizing an integral functional $J(x, u)$ over trajectories of the system.

Reviewer: [Hector O. Fattorini \(Los Angeles\)](#)

MSC:

- [49N25](#) Impulsive optimal control problems
- [49J27](#) Existence theories for problems in abstract spaces
- [34G20](#) Nonlinear differential equations in abstract spaces
- [93C25](#) Control/observation systems in abstract spaces
- [34A37](#) Ordinary differential equations with impulses
- [49J15](#) Existence theories for optimal control problems involving ordinary differential equations

Cited in **7** Documents

Keywords:

control of impulsive evolution equations; optimal control; Lagrange problems

Full Text: [DOI](#)

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