Lee, Taeyoung; Leok, Melvin; McClamroch, N. Harris
Global formulations of Lagrangian and Hamiltonian dynamics on manifolds. A geometric approach to modeling and analysis. (English) Zbl 1381.70005

The starting point of this impressive textbook is the important fact that there are remarkable situations where the variables that describe a dynamical system do not lie in a vector space (i.e., a simple flat algebraic structure) but rather lie in a geometrical setting allowing the differential calculus, namely a differential manifold.

The first chapter presents the necessary mathematical background. The second chapter concerns kinematics. Chapter 3 deals with classical Lagrangian and Hamiltonian mechanics (here classical refers to the Euclidean space \(\mathbb{R}^n\)). Starting with Chapter 4 the curved framework is considered. Chapter 4 is devoted to \((S^1)^n\), Chapter 5 to \((S^2)^n\), Chapter 6 to the Lie group \(SO(3)\) and Chapter 7 to the Lie group \(SE(3)\).

Having these settings at hand, Chapter 8 is devoted to the general Lagrangian and Hamiltonian dynamics on manifolds. Chapter 9 turns to the rigid and multi-body systems while the last chapter concerns with deformable multi-body systems. There are two appendices: “Fundamental lemmas of the calculus of variations” and “Linearization as an approximation to Lagrangian dynamics on a manifold”. Each chapter ends with problems and exercises.

In conclusion, this book is extremely useful for each reader who wishes to develop a modern knowledge of analytical mechanics.

Reviewer: Mircea Crâşmăreanu (Iaşi)

MSC:

- 70-02 Research exposition (monographs, survey articles) pertaining to mechanics of particles and systems
- 37-02 Research exposition (monographs, survey articles) pertaining to dynamical systems and ergodic theory
- 37Jxx Dynamical aspects of finite-dimensional Hamiltonian and Lagrangian systems
- 70Hxx Hamiltonian and Lagrangian mechanics

Keywords:
Lagrangian and Hamiltonian dynamics on manifolds; Lie group; geometric mechanics

Full Text: DOI