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**Multiplicity-induced-dominancy for delay-differential equations of retarded type.** (English)

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Consider a delay equation of the form

$$y^{(n)}(t) + \sum_{k=0}^{n-1} a_k y^{(k)}(t) + \sum_{k=0}^{n-1} \alpha_k y^{(k)}(t - \tau) = 0$$

with real coefficients and  $\tau > 0$ . The related characteristic function is defined as

$$\Delta(s) = s^n + \sum_{k=0}^{n-1} a_k + e^{-s\tau} \sum_{k=0}^{n-1} \alpha_k s^k.$$

Let  $s_0 \in \mathbb{R}$ . It is obtained a criterion for  $s_0$  to be a root of multiplicity  $2n$  of  $\Delta(s)$ . The conditions for  $s_0$  to be a strictly dominant root are proved.

If  $s_0$  is a root of multiplicity  $2n$  of  $\Delta(s)$ , then the trivial solution is exponentially stable if  $a_{n-1} > -n^2/\tau$ .

Some applications for linear control systems are given.

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#### MSC:

- [34K20](#) Stability theory of functional-differential equations
- [34K06](#) Linear functional-differential equations
- [34K35](#) Control problems for functional-differential equations
- [93D15](#) Stabilization of systems by feedback
- [33C90](#) Applications of hypergeometric functions

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#### Keywords:

time-delay functional-differential equation, stability, confluent hypergeometric function

#### Software:

DLMF; p3delta; Python

**Full Text:** [DOI](#) [arXiv](#)

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